

Breast segmentation

FE-based Heterogeneous Digital Volume Correlation to Measure Large Deformations of Breast's Soft Tissues

T. Lavigne, A. Mazier, A. Perney, S.P.A Bordas, F. Hild, J. Lengiewicz



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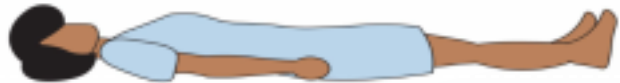
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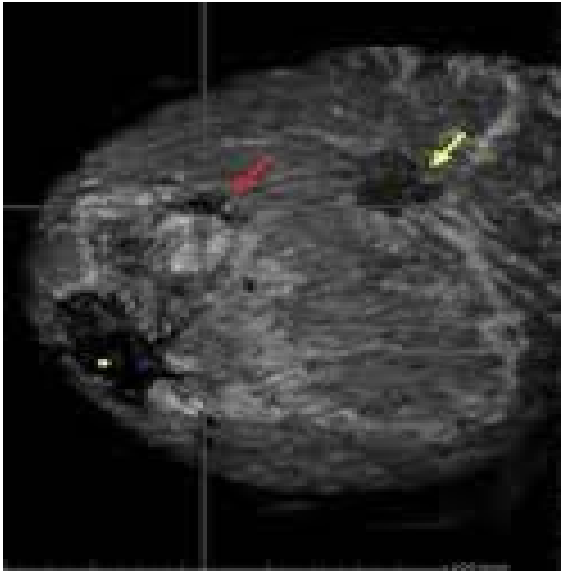
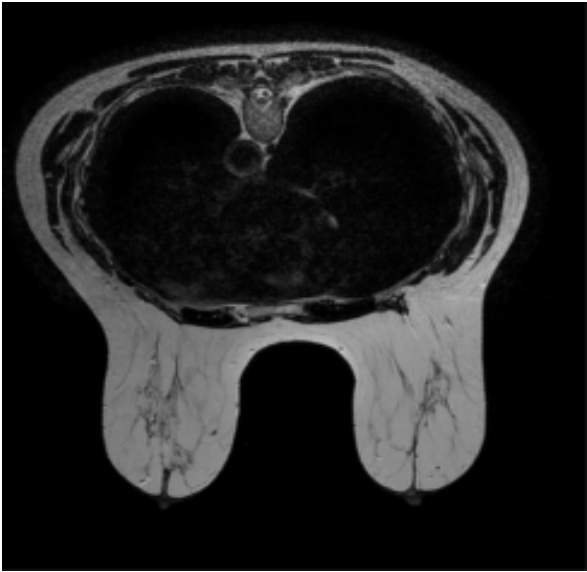
Preoperative imaging



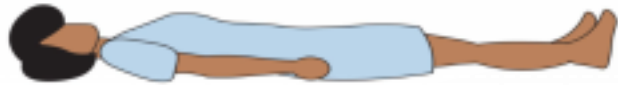
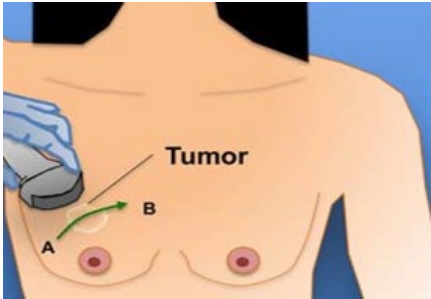
Surgery



[Gavaghan et al., 2008; Lee et al., 2010; Eiben et al., 2016; Mazier et al., 2021]



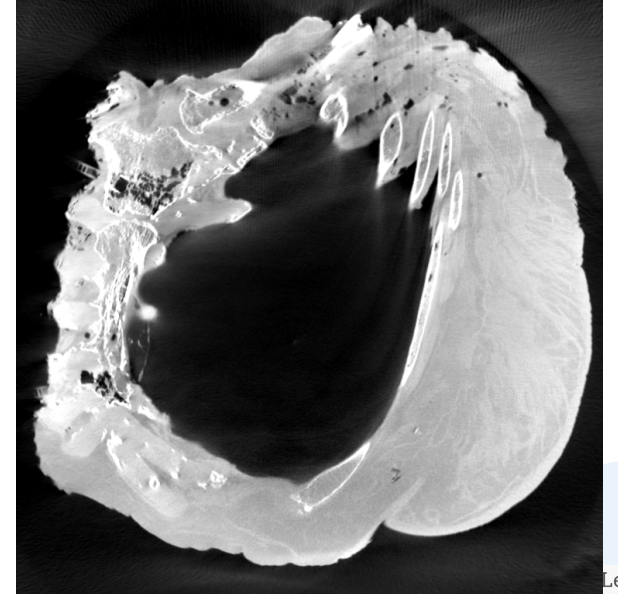
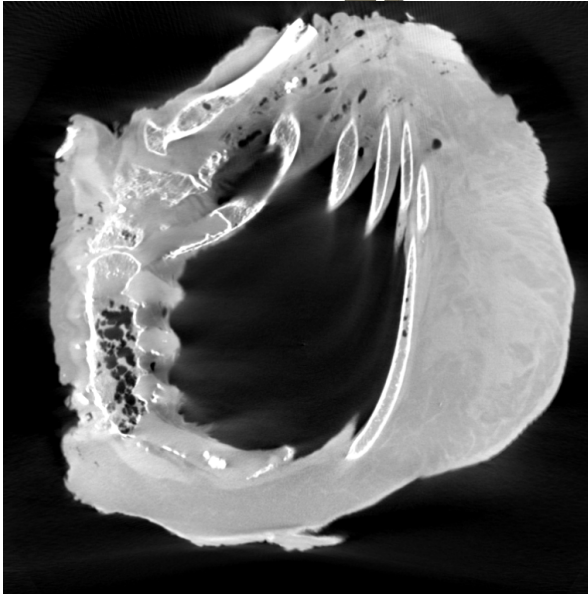
[Duraes et al., 2019]



Objective



**Predict the deformation from
one configuration to another**



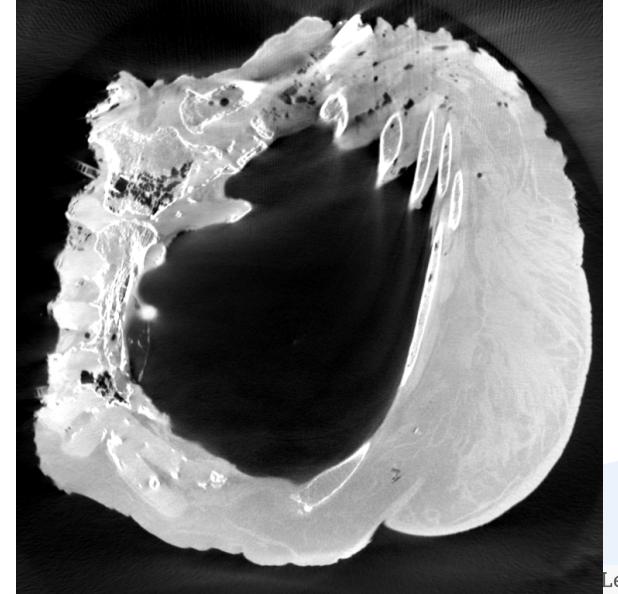
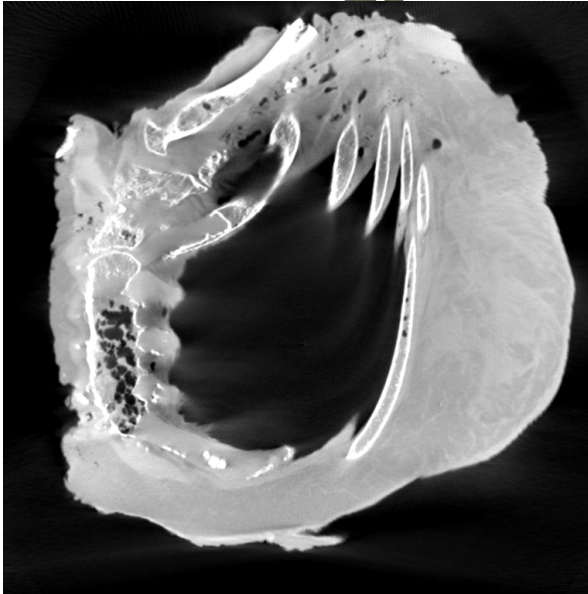
Objective



**Predict the deformation from
one configuration to another**

- Measure the full displacement field [Lavigne et al., 2022]

(FE-Based regularized DVC)

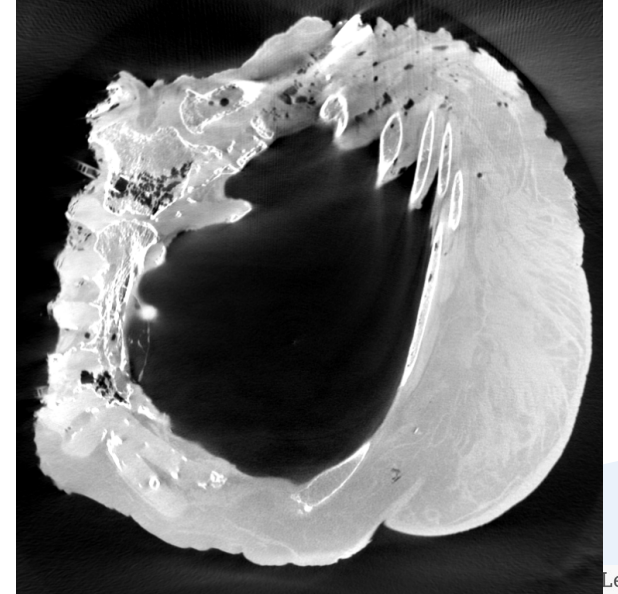
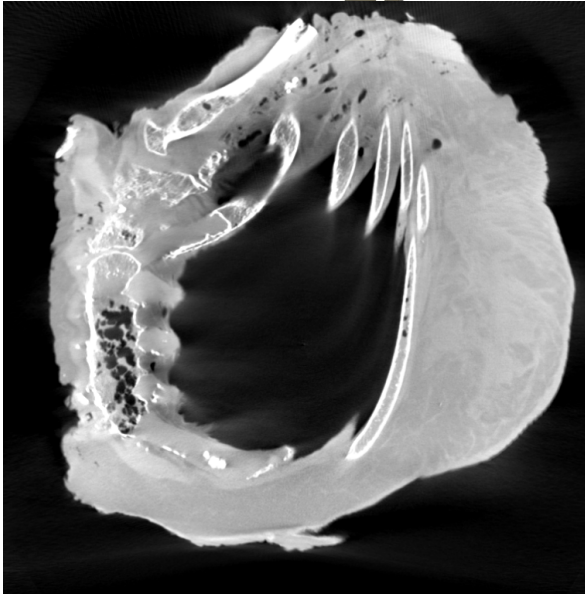


Objective



**Predict the deformation from
one configuration to another**

- Measure the full displacement field [Lavigne et al., 2022]
- Identify the patient-specific material properties [Lavigne et al., 2022]



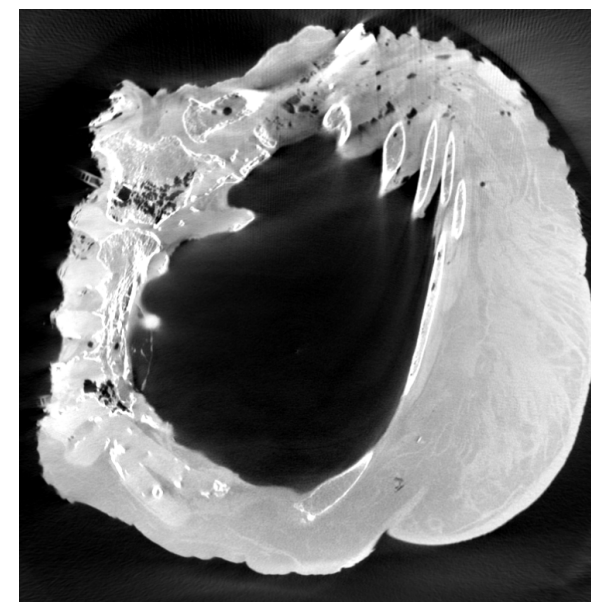
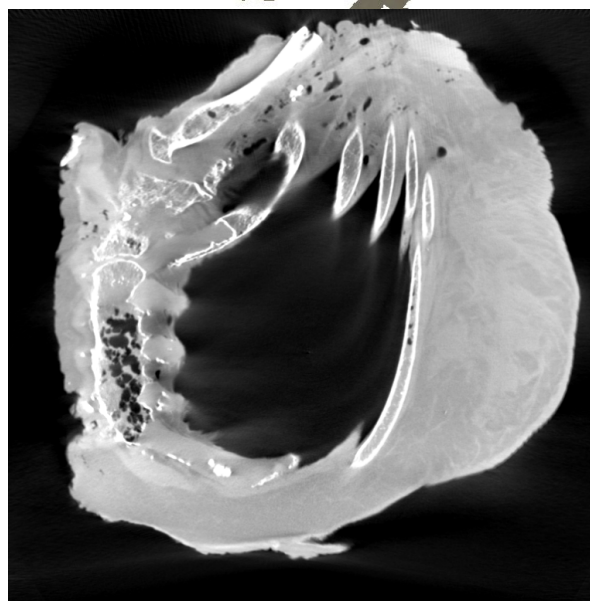
Objective



**Predict the deformation from
one configuration to another**

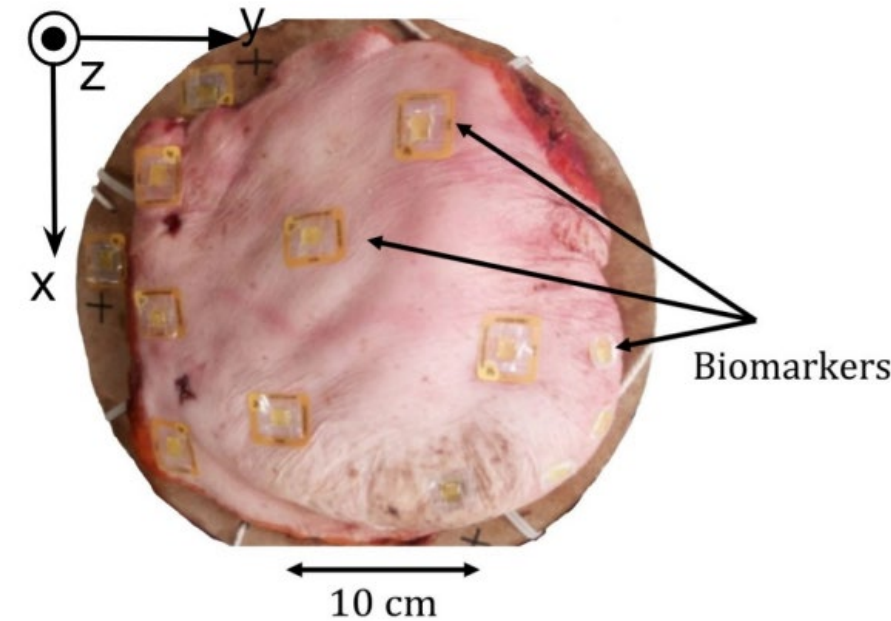


- Measure the full displacement field [Lavigne et al., 2022]
- Identify the patient-specific material properties [Lavigne et al., 2022]
- Surrogate model to obtain real-time predictions for any configuration [Deshpande et al., 2022]



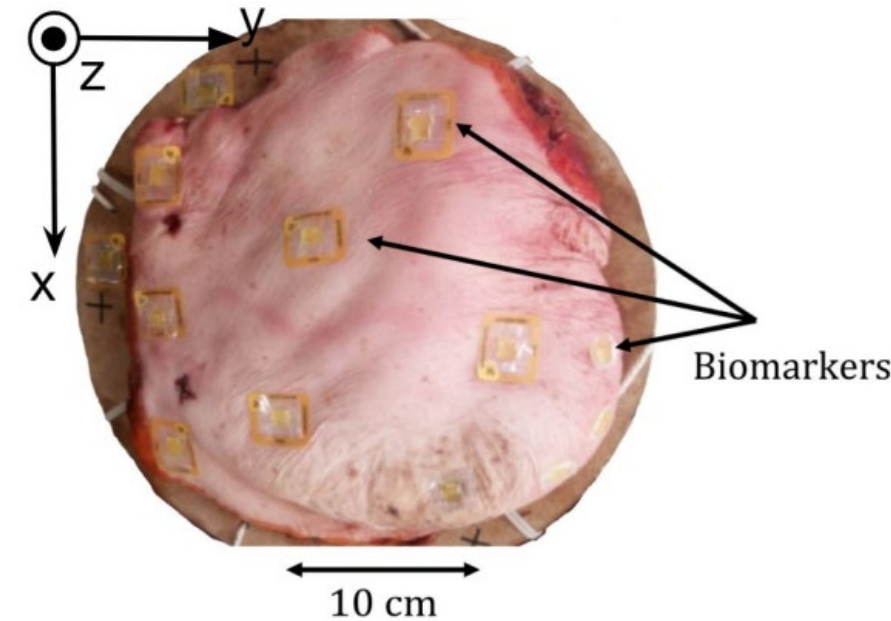
Material and Methods

- Female left **quarter of thorax** injected with physiological serum **attached to a wooden plate** with **4 plastic bands**



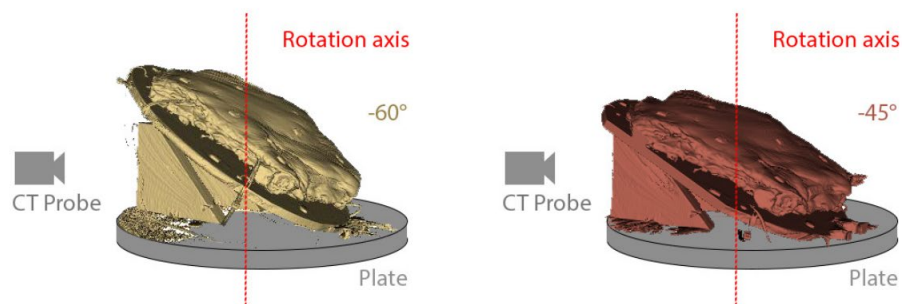
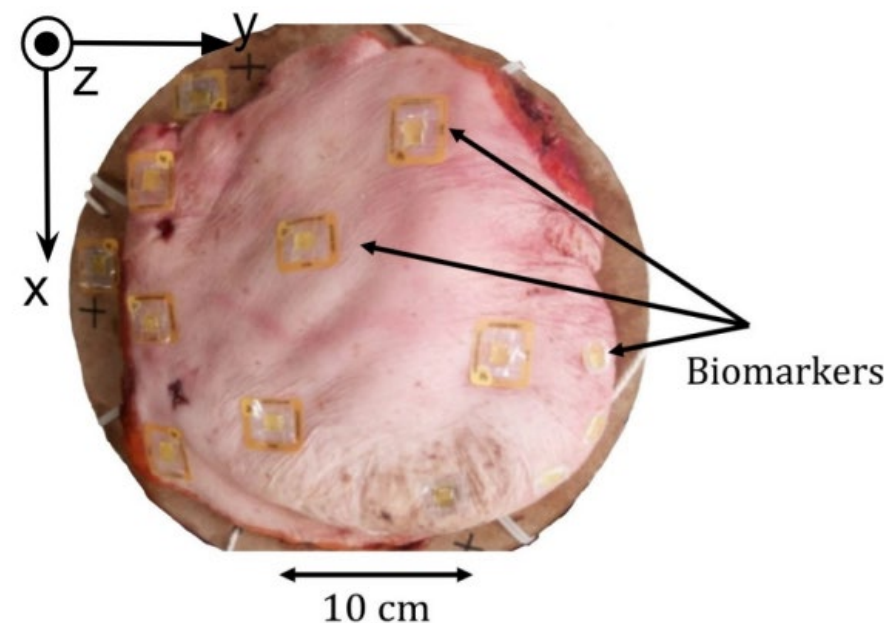
Material and Methods

- Female left **quarter of thorax** injected with physiological serum **attached to a wooden plate** with **4 plastic bands**
- **15 biomarkers** (in yellow) on the surface and inside the volume

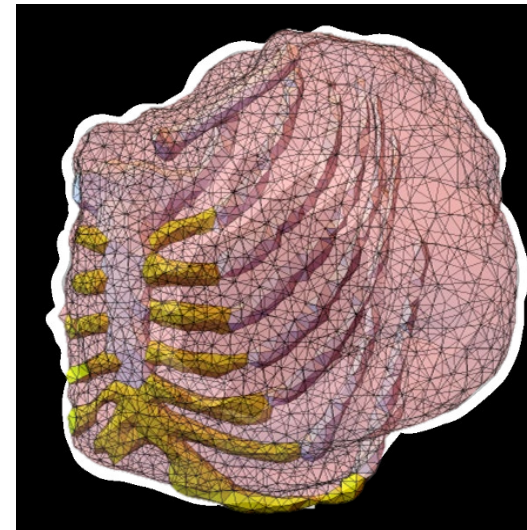
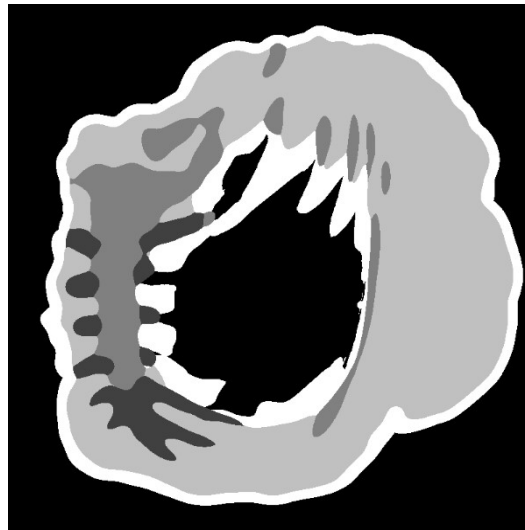
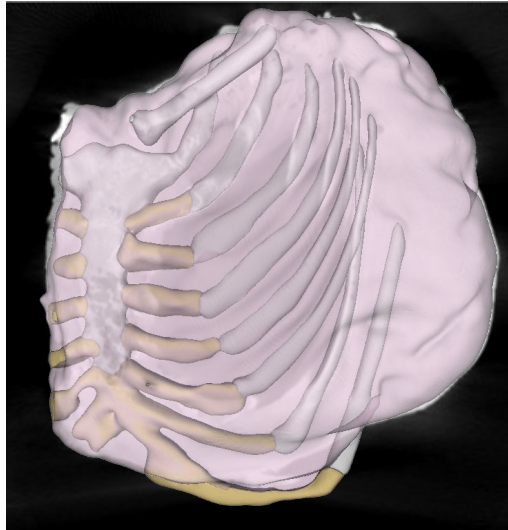


Material and Methods

- Female left **quarter of thorax** injected with physiological serum **attached to a wooden plate** with **4 plastic bands**
- **15 biomarkers** (in yellow) on the surface and inside the volume
- **Micro-computed tomography** with an RX Solutions machine (0.34 mm resolution)
- Acquisition in **multiple orientations**.
Study deals with **-60°** and **-45°** in the axial plane



Material and Methods



Mesh creation:

- Based on the gray levels, phases are identified
- A mask image is created
- Meshes are courtesy of **Synopsys**

Material and Methods

Heterogeneous regularised FE-DVC:

Conservation of gray levels:
$$\Phi_c^2 = \sum_{\text{ROI}} \left(I_0(\mathbf{x}) - I_t(\mathbf{x} + \mathbf{u}(\mathbf{x})) \right)^2$$

Material and Methods

Heterogeneous regularised FE-DVC:

Conservation of gray levels: $\Phi_c^2 = \sum_{\text{ROI}} \left(I_0(x) - I_t(x + \mathbf{u}(x)) \right)^2$

Mechanical regularization:
$$\begin{cases} [\mathbf{K}]\{\mathbf{v}\} = \{\mathbf{f}_{\text{res}}\} \\ \Phi_m^2 = \|\{\mathbf{f}_{\text{res}}\}\|^2 = \{\mathbf{v}\}^T [\mathbf{K}]^T [\mathbf{K}] \{\mathbf{v}\} \end{cases}$$

Material and Methods

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$\Phi_{tot}^2 = \Phi_c^2 + w_m \Phi_m^2$

Material and Methods

Heterogeneous regularised FE-DVC:

Elastic **contrast**:

- Eb : 5 to 50 GPa

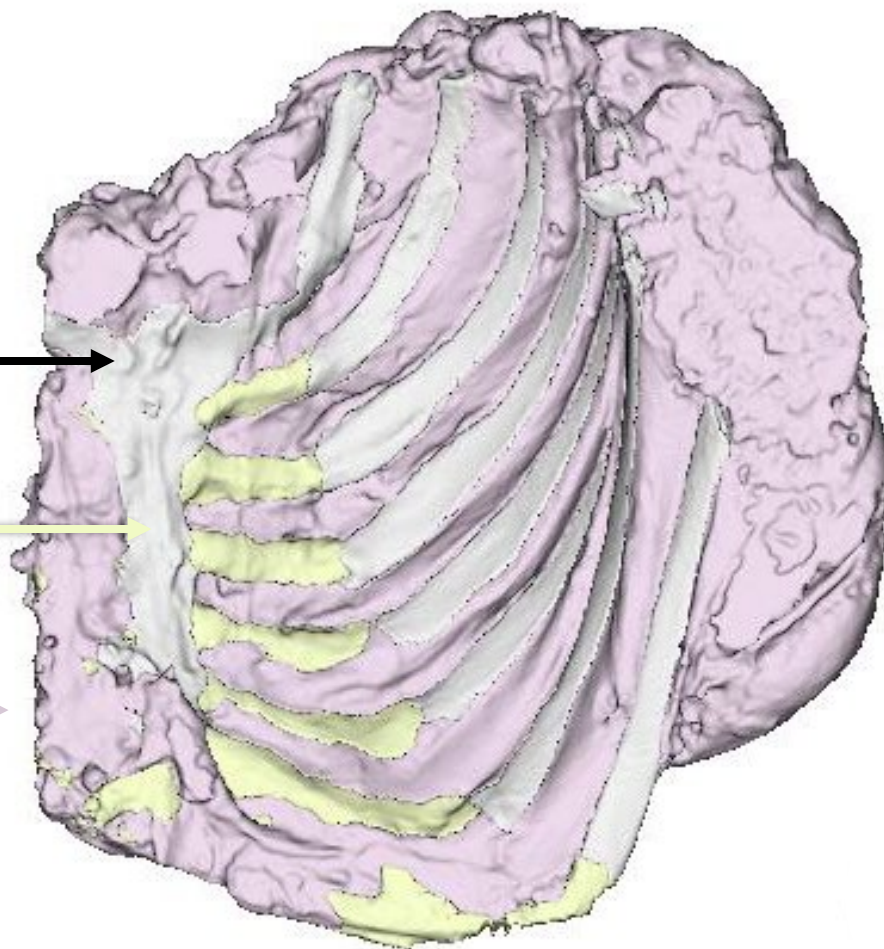
[Rho et al., 1993; Hunt et al., 1998; Seedhom et al., 2004]

- Ec : 8 to 40 MPa

[Forman and Kent, 2011; Huwe et al., 2018; Griffin et al., 2020]

- Et : 0.2 to 28 kPa

[Payan and Ohayon, 2017; Mîra et al., 2018]

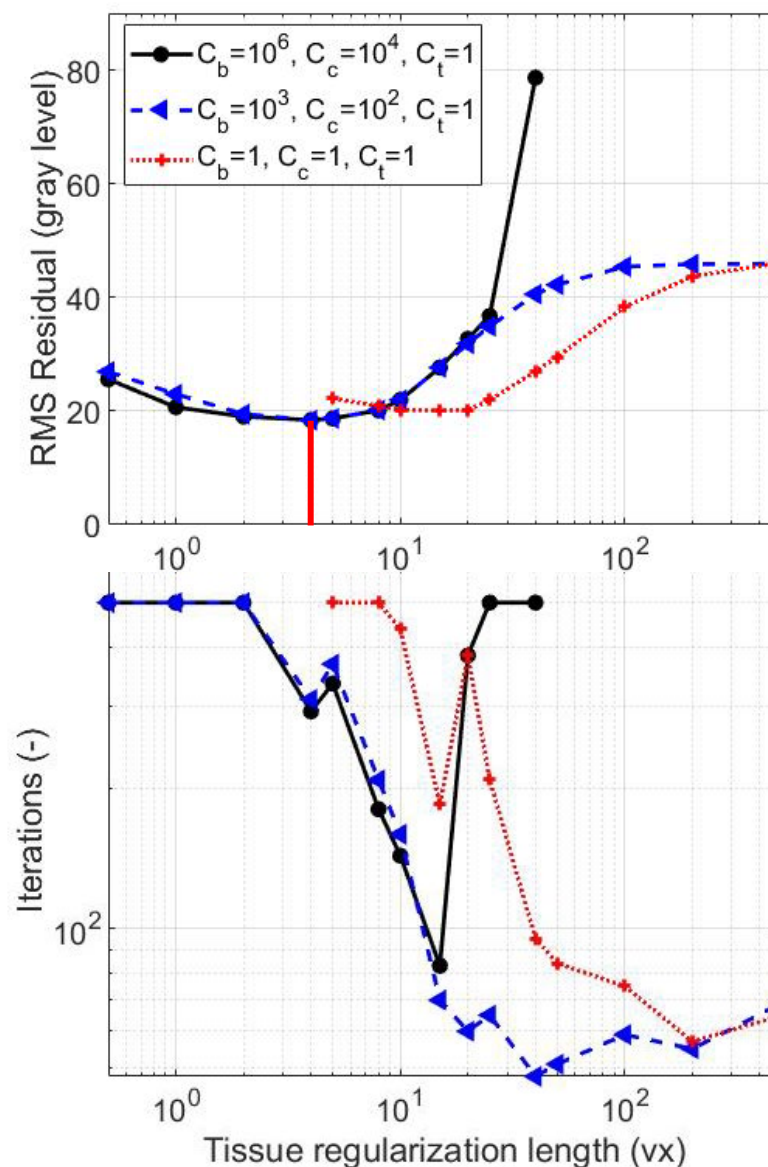


$C_b = 10^6$, $C_c = 10^4$ and $C_t = 1$

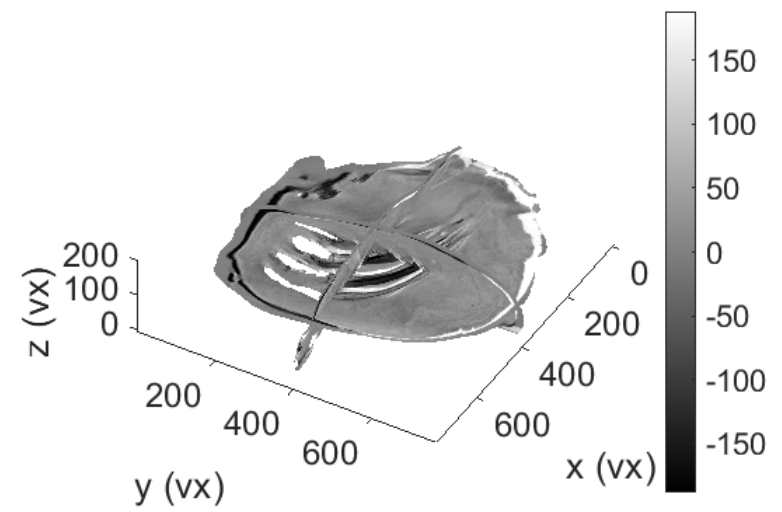
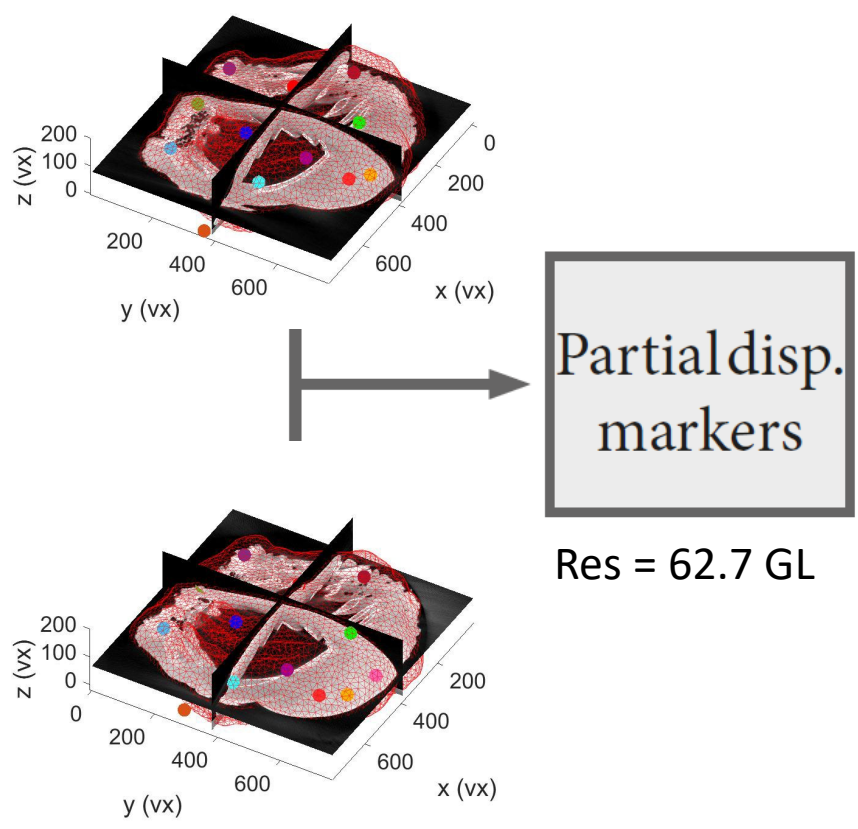
Material and Methods

Convergence analysis:

- $\ell_{\text{reg}} \leq 3v_x$: No convergence for the L^2 norm
- $\ell_{\text{reg}} \geq 40 v_x$: non-physical regularization & bad conditioning of the DVC Hessian matrix
- $\ell_{\text{reg}} = 4v_x$ was kept with the highest contrast



3-step procedure:



[Lavigne et al., 2022]

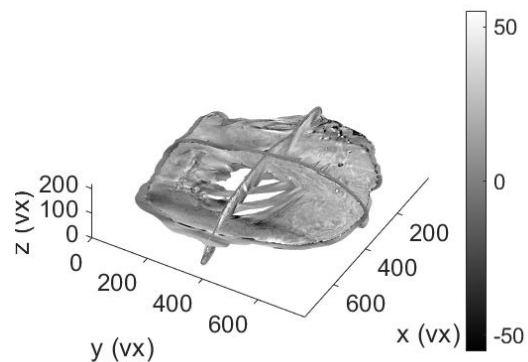
3-step procedure:



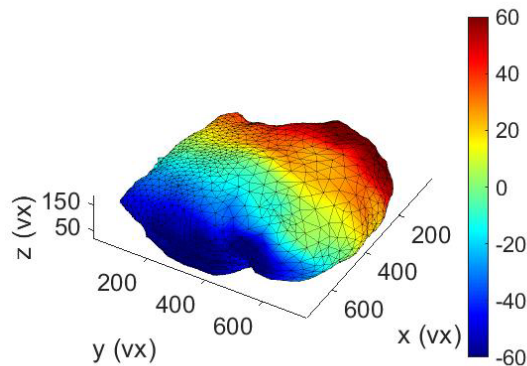
3-step procedure:



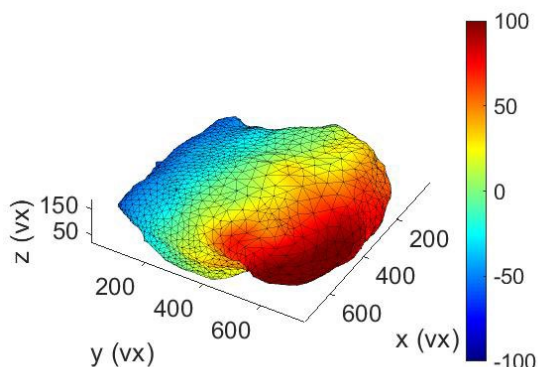
Results and Discussion



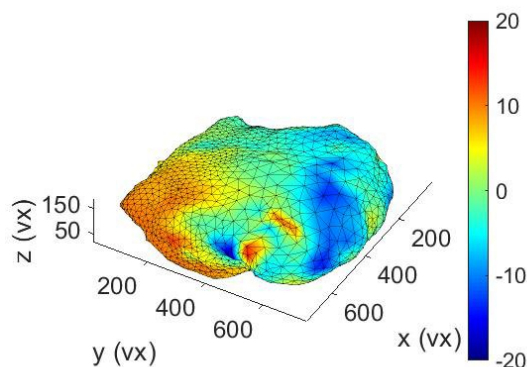
Residuals (gray levels)



u_x (voxels)



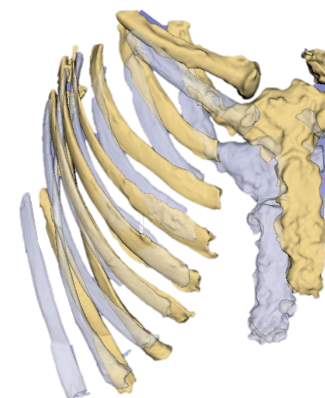
u_y (voxels)



u_z (voxels)

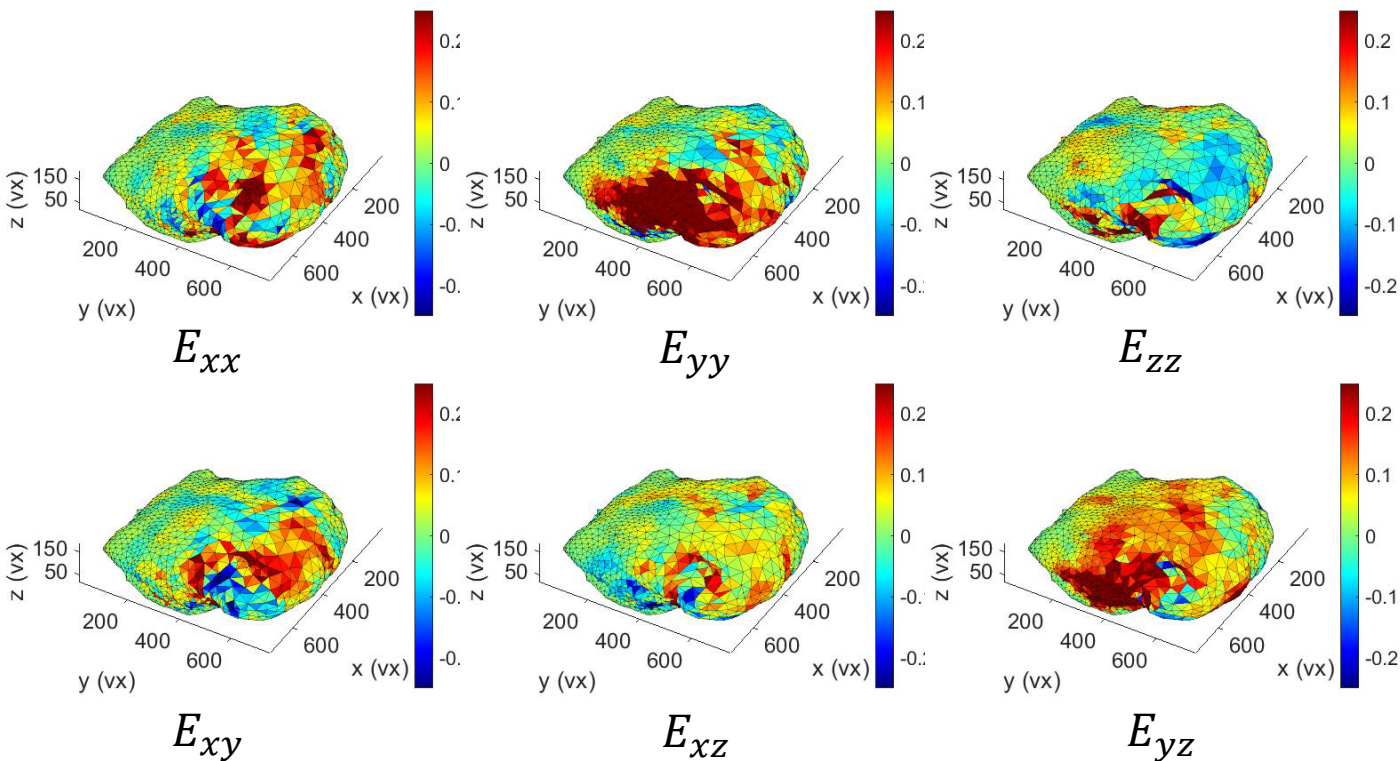
Final RMS residual was 18.3 GL

Displacement includes rigid motion



[Lavigne et al., 2022]

Results and Discussion

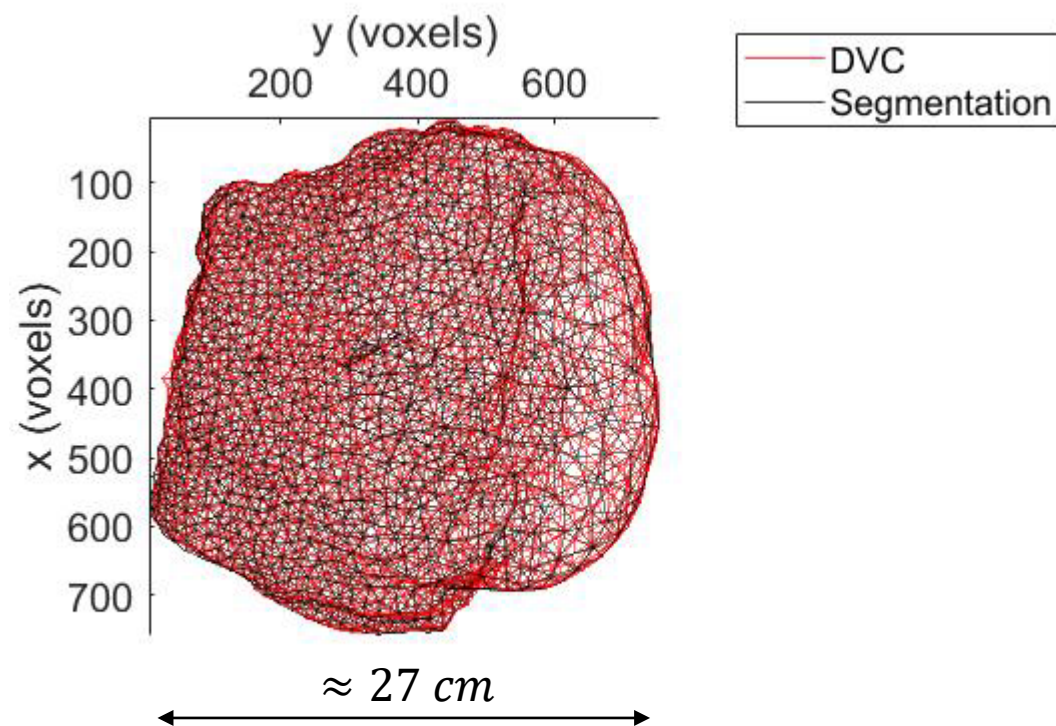


Green-Lagrange strains:

- Large deformation (>25%)
- Shear in the fold

[Lavigne et al., 2022]

Results and Discussion



Accurate displacement field (root mean square error $< 3 \text{ mm}$)

Phase	RMSE (mm)
Soft tissue	2.2 (2.3)
Cartilage	3.1 (3.2)
Bones	2.6 (2.7)

[Lavigne et al., 2022]

Conclusion and limitations

- From **micro-computed tomographies**, computation of the **full field displacement** between 2 complex configurations using **heterogeneous regularized DVC**
- 3-step pipeline has been developed
- The results are deemed trustworthy, supporting the feasibility of its application for breast large deformations

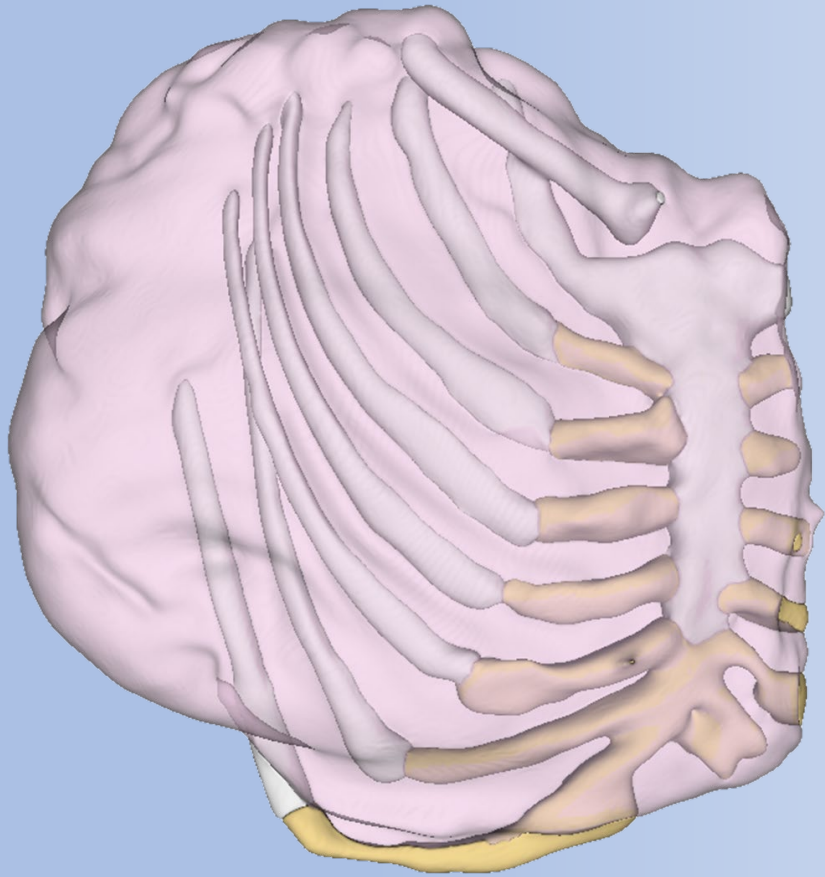
- *Ex-vivo* \neq *in-vivo* tissues
- Low number of scans and single patient
- Consider body forces
- User uncertainties

Acknowledgments

This study was supported by the European Union's Horizon 2020 research and innovation program under grant agreement No 811099, the Marie Skłodowska-Curie, Luxembourg grant agreement No. 764644, and the FNR Project No. C20/MS/14782078/QuaC. JL would like to acknowledge the support from EU Horizon 2020 Marie Skłodowska Curie Individual Fellowship MOrPhEM under Grant 800150. The medical images used in the present study were obtained at Hopital Arnaud de Villeneuve, Département de Gynécologie Obstétrique in collaboration with Dr. Gauthier Rathat, Prof. Guillaume Captier, and AnatoScope. The authors would like to thank Synopsys for its support in providing access to the Simpleware software to generate the meshes used in this project, and RX-Solutions for their support and answers about the machine settings that were used. Last, the authors sincerely thank the person who donated her body to science so that anatomical research could be performed.

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Breast segmentation

Thanks for your attention

Do you have any questions?



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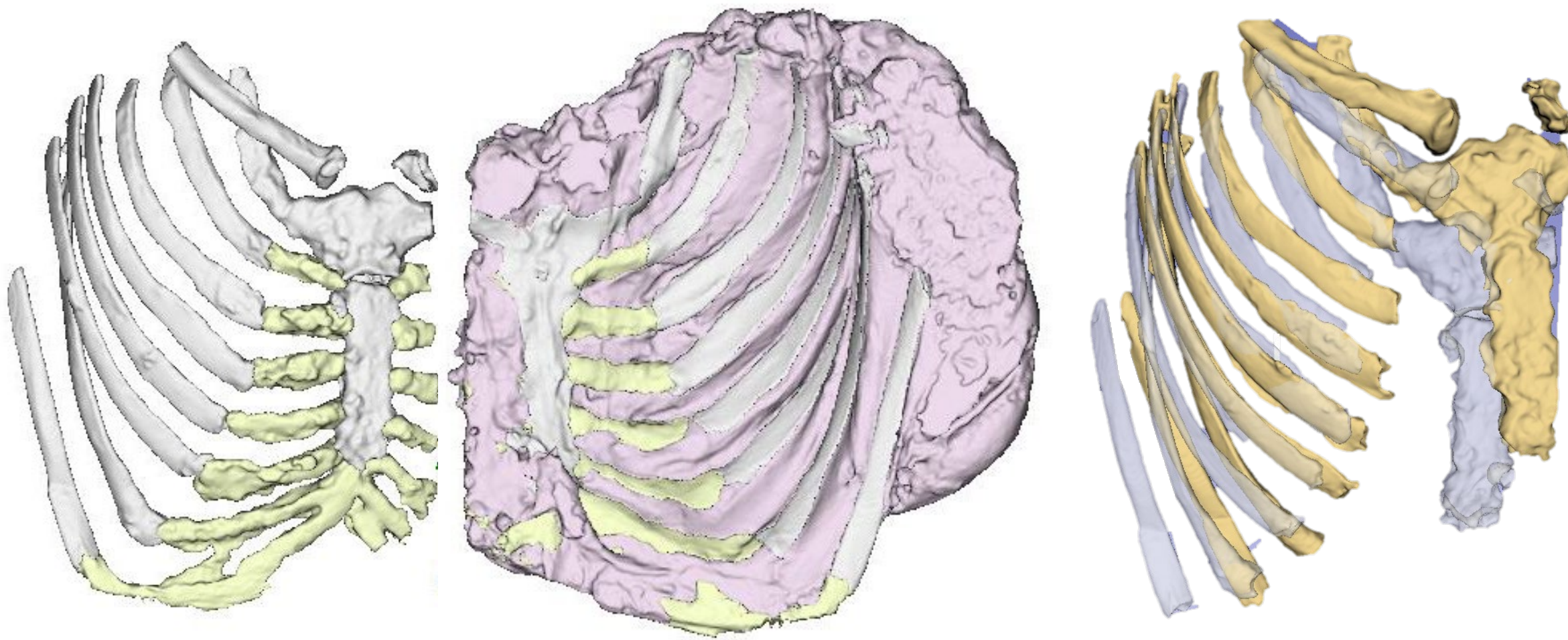
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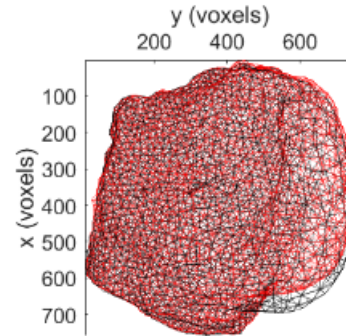
Appendix: Segmentation



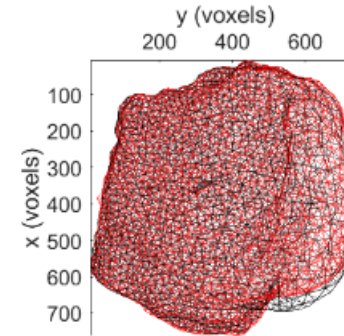
Appendix: DVC hardware parameters

Orientation	−60°	−45°
Tomograph	EasyTom 150 (RX Solution)	EasyTom 150 (RX Solution)
Target/Anode	W (reflection mode)	W (reflection mode)
Voltage	120 kV	120 kV
Current	202 μ A	202 μ A
Focal spot size	50 μ m	50 μ m
Tube to detector	610 mm	610 mm
Tube to object	430 mm	430 mm
Detector	Varian 25 \times 20 cm	Varian 25 \times 20 cm
Definition	1920 \times 1536 pixels	1920 \times 1536 pixels
Projection definition	1840 \times 728 pixels	1840 \times 728 pixels
Number of projections	2111	1407
Angular amplitude	360°	360°
Frame average	15 per projection	15 per projection
Frame rate	30 fps	30 fps
Acquisition duration	28 min 08 s	18 min 40 s
Reconstruction algorithm	Filtered back-projection	Filtered back-projection
Filter	Tukey (75%)	Tukey (0%)
Gray levels amplitude	8 bits	8 bits
Volume size	768 \times 781 \times 216 voxels (after crop)	768 \times 781 \times 216 voxels (after crop)
Field of view	261.12 \times 265.54 \times 73.44 mm ³ (after crop)	261.12 \times 265.54 \times 73.44 mm ³ (after crop)
Image scale	0.34 mm/voxel	0.34 mm/voxel

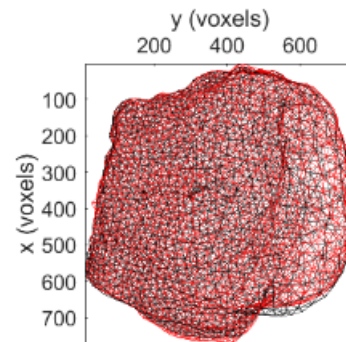
Appendix: Breast DVC convergence



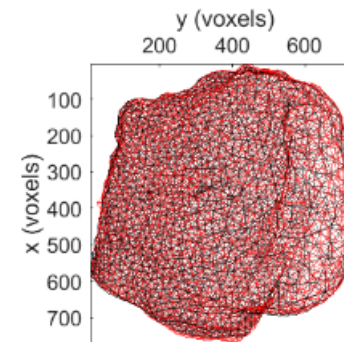
(a) $\ell_{reg}=500$ vx



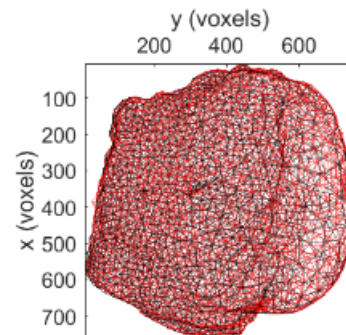
(b) $\ell_{reg}=200$ vx



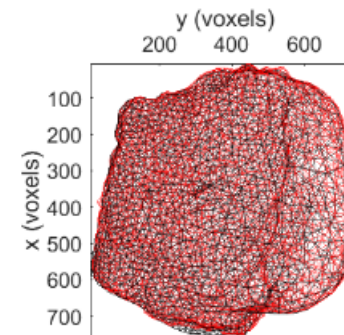
(c) $\ell_{reg}=100$ vx



(d) $\ell_{reg}=50$ vx

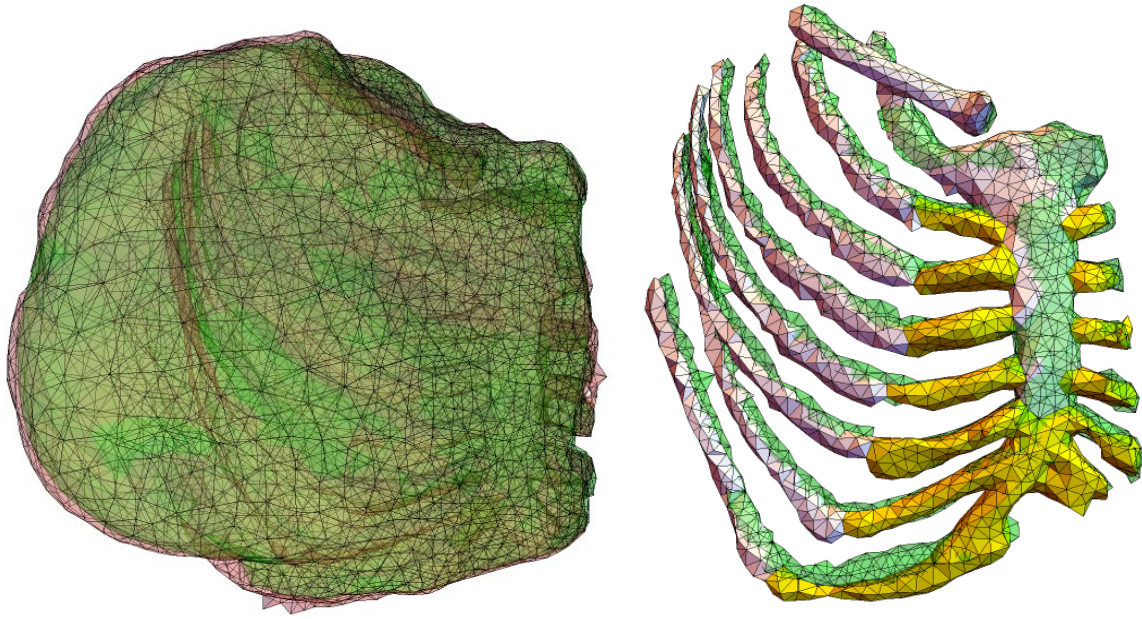


(e) $\ell_{reg}=20$ vx



(f) $\ell_{reg}=5$ vx

Appendix: Breast DVC results



DVC applied to -60° configuration (**green**) and segmentation in -45°

$$\text{RMSE}^2 = \frac{1}{N} \sum_{i=1}^N \left(\mathbf{x}_i^{\text{DVC}} - \mathcal{P}^{\text{seg}}(\mathbf{x}_i^{\text{DVC}}) \right)^2$$

Phase	RMSE (mm)
Soft tissue	2.31
Cartilage	3.18
Bones	2.72

Appendix: Gravity identification

$$\tilde{\mathbf{g}} = \begin{pmatrix} 0 \\ -9.81 \\ 0 \end{pmatrix}_{(X_m, Y_m, Z_m)}$$

$$\mathbf{R}_x = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos(\theta_x) & -\sin(\theta_x) & 0 \\ 0 & \sin(\theta_x) & \cos(\theta_x) & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}_{(X_m, Y_m, Z_m)}$$

$$\mathbf{R}_y = \begin{pmatrix} \cos(\theta_y) & 0 & \sin(\theta_y) & 0 \\ 0 & 1 & 0 & 0 \\ -\sin(\theta_y) & 0 & \cos(\theta_y) & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}_{(X_m, Y_m, Z_m)}$$

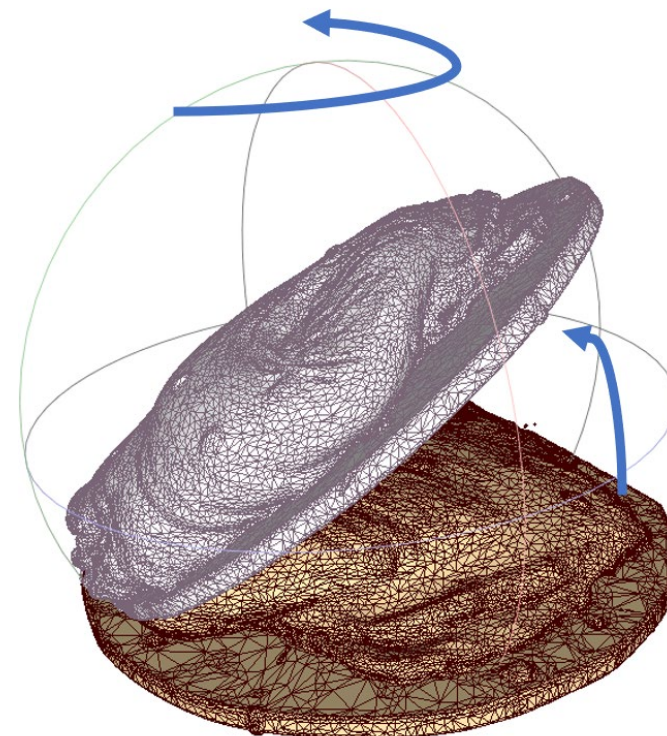
$$\mathbf{R}_z = \begin{pmatrix} \cos(\theta_z) & -\sin(\theta_z) & 0 & 0 \\ \sin(\theta_z) & \cos(\theta_z) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}_{(X_m, Y_m, Z_m)}$$

$$\mathbf{T} = \begin{pmatrix} 1 & 0 & 0 & t_x \\ 0 & 1 & 0 & t_y \\ 0 & 0 & 1 & t_z \\ 0 & 0 & 0 & 1 \end{pmatrix}_{(X_m, Y_m, Z_m)}$$

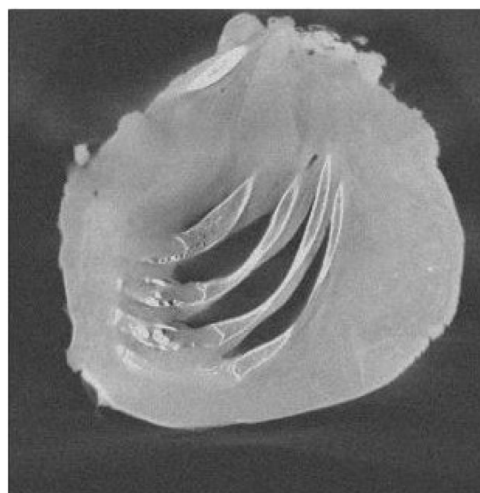
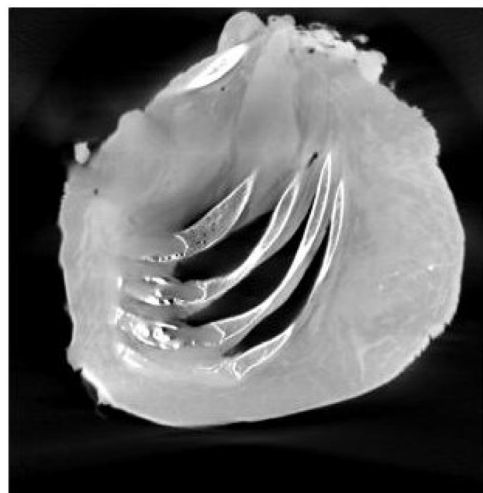
$$\tilde{\mathbf{P}} = \mathbf{R}_z \cdot \mathbf{R}_y \cdot \mathbf{R}_x \cdot \mathbf{T} \cdot \mathbf{P}$$

$$\mathbf{g} = (\mathbf{R}_z \cdot \mathbf{R}_y \cdot \mathbf{R}_x \cdot \mathbf{T})^{-1} \cdot \tilde{\mathbf{g}}$$

$$\Leftrightarrow \mathbf{g} = \mathbf{T}^{-1} \cdot \mathbf{R}_x^T \cdot \mathbf{R}_y^T \cdot \mathbf{R}_z^T \cdot \tilde{\mathbf{g}}$$



Appendix: Uncertainty quantification

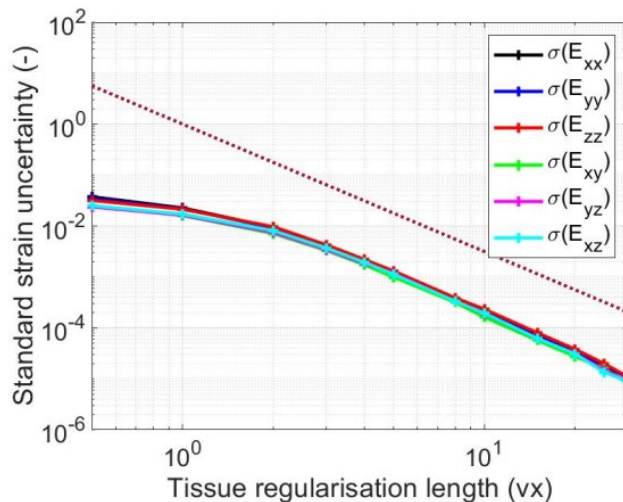
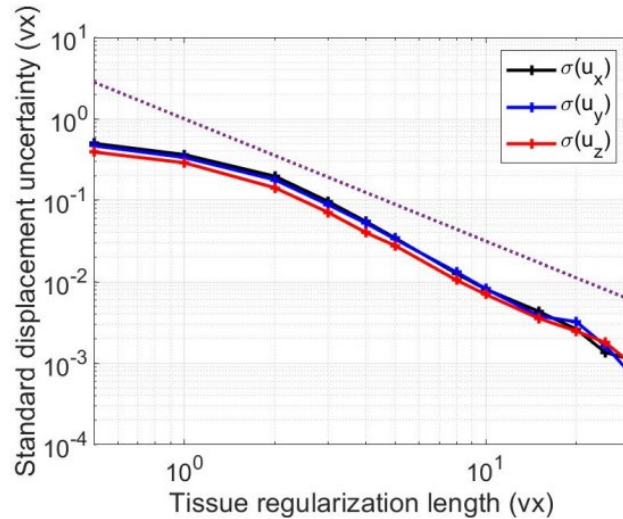


Uncertainty evaluation

- White Gaussian noise was added to the translated reference volume.
- Registering to the reference volume.
- Displacement uncertainties = standard deviations of nodal displacements.
- Regularized DVC => the fine mesh was not altered but the regularization length ℓ_{reg} was varied [Leclerc et al., 2011; Taillandier-Thomas et al., 2014].

[Lavigne et al., 2022]

Appendix: Uncertainty quantification



Uncertainty evaluation

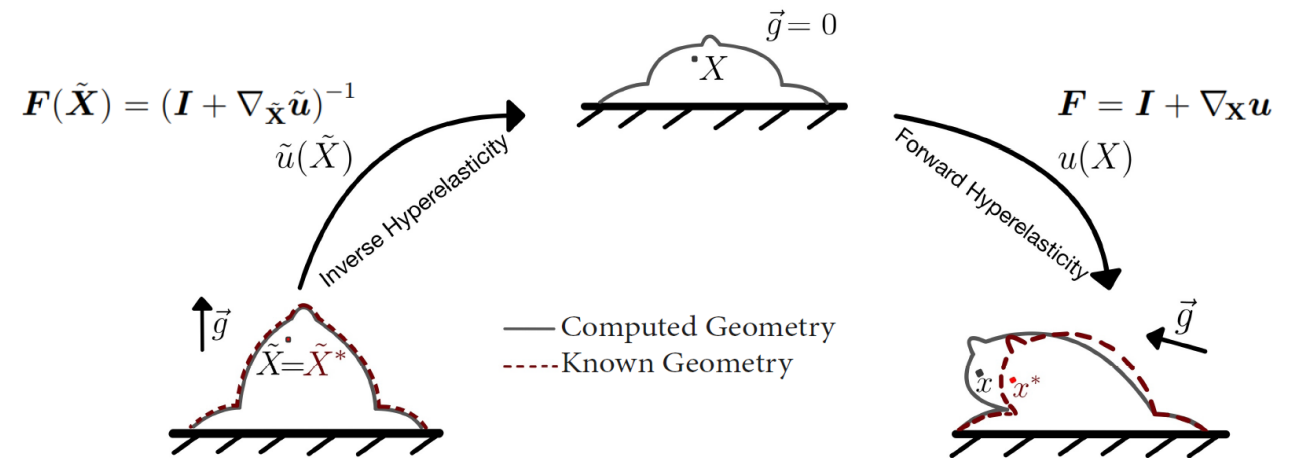
- The displacement power law interpolation with exponent -1.5 corresponding to Gaussian noise is recovered
- The strain power law interpolation with exponent -2.5 corresponding to Gaussian noise is recovered
- $4v_x$ regularization length leads to $0.1v_x$ displacement uncertainty, which is acceptable given the previous results.

[Lavigne et al., 2022]

Appendix: Parameter identification FE framework

Input: 2 loaded configurations
(2 benchmark problems)

Inverse-forward FE model
(Neo-Hookean law & contact)



[Lavigne et al., 2022]